


Matrix Eigenvalues and Eigenvectors

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Outline

- Review last lecture
- Definition of eigenvalues and eigenvectors: $\mathbf{Ax} = \lambda\mathbf{x}$
- Use $\text{Det}[\mathbf{A} - \mathbf{I}\lambda] = 0$ to find eigenvalues
- Solve $[\mathbf{A} - \mathbf{I}\lambda] \mathbf{x} = 0$ to get eigenvectors to within a multiplicative constant
- Number of different eigenvalues and eigenvectors




Review Last Lecture

- Gauss elimination for solving equations and determining rank (number of linearly independent rows or columns)
- Solution of $\mathbf{Ax} = \mathbf{b}$
 - No solutions unless $\text{rank } \mathbf{A} = \text{rank } [\mathbf{A} \ \mathbf{b}]$
 - Unique if $\text{rank } \mathbf{A} = \text{rank } [\mathbf{A} \ \mathbf{b}] = \text{number of unknowns}$ (infinite if $\text{rank} < \text{unknowns}$)
 - Homogenous equations, $\mathbf{Ax} = \mathbf{0}$: only solution is $\mathbf{x} = \mathbf{0}$ unless $\text{Det } \mathbf{A} = 0$ (same as saying $\text{Rank } \mathbf{A} < n$)




Uses of Eigenvalues

- In electrical and mechanical networks, provides fundamental frequencies
- Shows coordinate transformations appropriate for physical problems
- Provides way to express network problem as diagonal matrix
- Transformations based on eigenvectors used in some solutions of $\mathbf{Ax} = \mathbf{b}$



Eigenvalues and Eigenvectors


- Basic definition (\mathbf{A} square): $\mathbf{Ax} = \lambda\mathbf{x}$
- \mathbf{x} is eigenvector, λ is eigenvalue
- Basic idea is that eigenvector is special vector of matrix \mathbf{A} ; multiplication of \mathbf{x} by \mathbf{A} produces \mathbf{x} multiplied by a constant
- $\mathbf{Ax} = \lambda\mathbf{x} \Rightarrow \mathbf{Ax} - \lambda\mathbf{x} = [\mathbf{A} - \mathbf{I}\lambda]\mathbf{x} = \mathbf{0}$
- Homogenous equations; requires $\text{Det} [\mathbf{A} - \mathbf{I}\lambda] = 0$ for solution other than $\mathbf{x} = \mathbf{0}$



$\text{Det}[\mathbf{A} - \mathbf{I}\lambda] = 0$

$$\text{Det}[\mathbf{A} - \mathbf{I}\lambda] = \text{Det} \begin{bmatrix} a_{11} - \lambda & a_{12} & a_{13} & \cdots & \cdots & a_{1n} \\ a_{21} & a_{22} - \lambda & a_{23} & \cdots & \cdots & a_{2n} \\ a_{31} & a_{32} & a_{33} - \lambda & \cdots & \cdots & a_{3n} \\ \vdots & \vdots & \vdots & \ddots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \ddots & \ddots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \cdots & \cdots & a_{nn} - \lambda \end{bmatrix} = 0$$

- $\text{Det}[\mathbf{A} - \mathbf{I}\lambda] = 0$ produces an n^{th} order equation that has n roots for λ . May have duplicate roots for eigenvalues.



Two-by-two Matrix Eigenvalues

- Quadratic equation with two roots for eigenvalues $\begin{vmatrix} a_{11} - \lambda & a_{12} \\ a_{21} & a_{22} - \lambda \end{vmatrix} = (a_{11} - \lambda)(a_{22} - \lambda) - a_{21}a_{12} = \lambda^2 - (a_{11} + a_{22})\lambda + a_{11}a_{22} - a_{21}a_{12} = 0$
- Eigenvalue solutions $\lambda = \frac{(a_{11} + a_{22}) \pm \sqrt{(a_{11} + a_{22})^2 - 4(a_{11}a_{22} - a_{21}a_{12})}}{2}$ (where $4(a_{11}a_{22} - a_{21}a_{12})$ is circled in red and labeled **Det A**)

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Two-by-two Matrix Eigenvalues

- Write $\sqrt{(a_{11} + a_{22})^2 - 4\text{Det } \mathbf{A}}$ as $\sqrt{\quad}$
- Add the two solutions to get $\lambda_1 + \lambda_2 = \frac{(a_{11} + a_{22}) + \sqrt{\quad}}{2} + \frac{(a_{11} + a_{22}) - \sqrt{\quad}}{2} = a_{11} + a_{22}$
- Multiply the two solutions to get $\lambda_1\lambda_2 = \frac{\left(\frac{(a_{11} + a_{22}) + \sqrt{\quad}}{2}\right)\left(\frac{(a_{11} + a_{22}) - \sqrt{\quad}}{2}\right) - (a_{11} + a_{22})^2 - (\sqrt{\quad})^2}{4} = \frac{(a_{11} + a_{22})^2 - (a_{11} + a_{22})^2 + 4\text{Det } \mathbf{A}}{4} = \text{Det } \mathbf{A}$

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Sum and Product

- The results on the previous slide apply to all matrix eigenvalues
- The sum of the eigenvalues is the sum of the diagonal elements of the matrix, called the trace of the matrix
- The product of the eigenvalues is the determinant of the matrix

$$\sum_{i=1}^n \lambda_i = \sum_{i=1}^n a_{ii} = \text{Trace } \mathbf{A} \quad \prod_{i=1}^n \lambda_i = \text{Det } \mathbf{A}$$

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Two-by-two Matrix Eigenvectors

- Two eigenvectors: $\mathbf{x}_{(1)} = [x_{(1)1} \ x_{(1)2}]^T$ and $\mathbf{x}_{(2)} = [x_{(2)1} \ x_{(2)2}]^T$ ($\mathbf{x}_{(j)} = [x_{(j)1} \ x_{(j)2}]^T$)
- Substitute each eigenvalue solution, λ_j , into $(\mathbf{A} - \lambda_j \mathbf{I})\mathbf{x} = \mathbf{0}$ to find all $\mathbf{x}_{(j)}$ components $(a_{11} - \lambda_j)x_{(j)1} + a_{12}x_{(j)2} = 0$
 $a_{21}x_{(j)1} + (a_{22} - \lambda_j)x_{(j)2} = 0$

Notation: y_i is component i of vector \mathbf{y} ; $\mathbf{z}_{(k)}$ is one vector in a set of vectors with components $z_{(k)i}$

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Two-by-two Eigenvectors II

- Eigenvector equations are homogeneous, so eigenvectors are determined only within a multiplicative constant
- Pick $x_{(j)1} = \alpha$ (arbitrary) $(a_{11} - \lambda_j)x_{(j)1} + a_{12}x_{(j)2} = 0$
 $a_{21}x_{(j)1} + (a_{22} - \lambda_j)x_{(j)2} = 0$

$$x_{(j)1} = \alpha \quad x_{(j)2} = \frac{(\lambda_j - a_{11})}{a_{12}} \alpha = \frac{a_{21}}{(\lambda_j - a_{22})} \alpha$$

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Two-by-two Example

- Find eigenvalues and eigenvectors of $\mathbf{A} = \begin{bmatrix} 1 & 5 \\ 0 & 2 \end{bmatrix}$

$$\text{Det}[\mathbf{A} - \mathbf{I}\lambda] = \begin{vmatrix} 1 - \lambda & 5 \\ 0 & 2 - \lambda \end{vmatrix} = 0$$

$$\text{Det}[\mathbf{A} - \mathbf{I}\lambda] = (1 - \lambda)(2 - \lambda) - (0)(5) = 0$$

- Solutions are $\lambda_1 = 2$ and $\lambda_2 = 1$

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Two-by-two Example Continued

- Find $\mathbf{x}_{(1)}$ components for $\lambda_1 = 2$ $\mathbf{A} = \begin{bmatrix} 1 & 5 \\ 0 & 2 \end{bmatrix}$
- Solve $[\mathbf{A} - \lambda\mathbf{I}]\mathbf{x} = \mathbf{0}$ for $\mathbf{x}_{(1)}$ components

$$(1-2)x_{(1)1} + 5x_{(1)2} = -x_{(1)1} + 5x_{(1)2} = 0$$

$$0x_{(1)1} + (2-2)x_{(1)2} = 0x_{(1)1} + 0x_{(1)2} = 0$$
- One equation in two unknowns
- Pick $x_{(1)2} = \alpha$ then $x_{(1)1} = 5\alpha$ from first equation
- Eigenvector $\mathbf{x}_{(1)}$ is $[5\alpha \ \alpha]^T$

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Two-by-two Example Concluded

- Next find $\mathbf{x}_{(2)}$ components for $\lambda_2 = 1$ $\mathbf{A} = \begin{bmatrix} 1 & 5 \\ 0 & 2 \end{bmatrix}$
- Same as approach for finding $\mathbf{x}_{(1)}$

$$(1-1)x_{(2)1} + 5x_{(2)2} = 0x_{(2)1} + 5x_{(2)2} = 0$$

$$0x_{(2)1} + (2-1)x_{(2)2} = 0x_{(2)1} + 1x_{(2)2} = 0$$
- Both equations give $x_{(2)2} = 0$
- Pick $x_{(2)1} = \beta$ (With $x_{(2)2} = 0$, $x_{(2)1}$ can be any value and still satisfy each equation)
- $\mathbf{x}_{(2)} = [\beta \ 0]^T$

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Check Two-by-two Example

$$\mathbf{A}\mathbf{x}_{(1)} = \begin{bmatrix} 1 & 5 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 5\alpha \\ \alpha \end{bmatrix} = \begin{bmatrix} (1)(5\alpha) + (5)(\alpha) \\ (0)(5\alpha) + (2)(\alpha) \end{bmatrix}$$

$$= \begin{bmatrix} 10\alpha \\ 2\alpha \end{bmatrix} = 2 \begin{bmatrix} 5\alpha \\ \alpha \end{bmatrix} = \lambda_1 \mathbf{x}_{(1)}$$

$$\mathbf{A}\mathbf{x}_{(2)} = \begin{bmatrix} 1 & 5 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} \beta \\ 0 \end{bmatrix} = \begin{bmatrix} (1)(\beta) + (5)(0) \\ (0)(\beta) + (2)(0) \end{bmatrix}$$

$$= \begin{bmatrix} \beta \\ 0 \end{bmatrix} = 1 \begin{bmatrix} \beta \\ 0 \end{bmatrix} = \lambda_2 \mathbf{x}_{(2)}$$

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Eigenvector Factors

- 2 x 2 example showed $\mathbf{A}\mathbf{x}_{(j)} = \lambda_j \mathbf{x}_{(j)}$ regardless of choice of α and β
- This is general result
- We can pick one eigenvector component; typical choices are to make eigenvector simple or a unit vector (with unit length)

$$\mathbf{x}_{(1)} = \begin{bmatrix} 5\alpha \\ \alpha \end{bmatrix} \quad \mathbf{x}_{(1)} = \begin{bmatrix} 5 \\ 1 \end{bmatrix} \quad \mathbf{x}_{(1)} = \begin{bmatrix} 5/\sqrt{26} \\ 1/\sqrt{26} \end{bmatrix} \quad \mathbf{x}_{(2)} = \begin{bmatrix} \beta \\ 0 \end{bmatrix} \quad \mathbf{x}_{(2)} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

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How Many Eigenvalues?

- An $n \times n$ matrix has $k \leq n$ distinct eigenvalues
- Algebraic multiplicity of an eigenvalue, M_{λ} , is the number of roots of $\text{Det}[\mathbf{A} - \lambda\mathbf{I}] = 0$ that have the same root, λ
- Geometric multiplicity, m_{λ} , of eigenvalue is number of linearly independent eigenvectors for this λ

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Multiple Eigenvalue Example

$$\mathbf{A} = \begin{bmatrix} 2 & 2 & -6 \\ 2 & -1 & -3 \\ -2 & -1 & 1 \end{bmatrix} \quad \mathbf{A} - \lambda\mathbf{I} = \begin{bmatrix} 2-\lambda & 2 & -6 \\ 2 & -1-\lambda & -3 \\ -2 & -1 & 1-\lambda \end{bmatrix}$$

$$\text{Det}(\mathbf{A} - \lambda\mathbf{I}) = (2-\lambda)(-1-\lambda)(1-\lambda) + (2)(-1)(-6) + (-2)(2)(-3) - (-2)(-1-\lambda)(-6) - (2)(2)(1-\lambda)$$

$$- (2-\lambda)(-1)(-3) = -\lambda^3 + 2\lambda^2 + \lambda - 2 + 12 + 12 + 12 + 12\lambda - 4 + 4\lambda - 6 + 3\lambda = -\lambda^3 + 2\lambda^2 + 20\lambda + 24 = 0$$

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Multiple Eigenvalue Example II

$Det(\mathbf{A} - \mathbf{I}\lambda) = (\lambda + 2)(\lambda + 2)(\lambda - 6) = 0$

- Solutions are $\lambda = 6, -2, -2$
- $\lambda = -2$ has algebraic multiplicity of 2
- Find eigenvector(s) from $(\mathbf{A} - \mathbf{I}\lambda_k)\mathbf{x}_{(k)} = \mathbf{0}$

$$\begin{bmatrix} 2-\lambda_k & 2 & -6 \\ 2 & -1-\lambda_k & -3 \\ -2 & -1 & 1-\lambda_k \end{bmatrix} \begin{bmatrix} x_{(k)1} \\ x_{(k)2} \\ x_{(k)3} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

• Look at $\lambda_k = -2$

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Multiple Eigenvalue Example III

$$\begin{bmatrix} 2-(-2) & 2 & -6 \\ 2 & -1-(-2) & -3 \\ -2 & -1 & 1-(-2) \end{bmatrix} \begin{bmatrix} x_{(k)1} \\ x_{(k)2} \\ x_{(k)3} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 4 & 2 & -6 \\ 2 & 1 & -3 \\ -2 & -1 & 3 \end{bmatrix} \begin{bmatrix} x_{(k)1} \\ x_{(k)2} \\ x_{(k)3} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

- Apply Gauss elimination to these equations
- Pick $x_{(k)3}$ and $x_{(k)2}$

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Multiple Eigenvalue Example IV

$$\begin{bmatrix} 4 & 2 & -6 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_{(k)1} \\ x_{(k)2} \\ x_{(k)3} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

• Pick $x_{(k)2}$ and $x_{(k)3}$ then $x_{(k)1} = \frac{6x_{(k)3} - 2x_{(k)2}}{4}$

- Pick $x_{(k)3} = 2$ and $x_{(k)2} = 0 \Rightarrow x_{(k)1} = 3$
- Pick $x_{(k)3} = 0$ and $x_{(k)2} = 2 \Rightarrow x_{(k)1} = -1$
- Two linearly independent eigenvectors for $\lambda = -2$

$$\mathbf{x}_{(1)} = \begin{bmatrix} 3 \\ 0 \\ 2 \end{bmatrix} \quad \mathbf{x}_{(2)} = \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}$$

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Continue Example for $\lambda_3 = 6$

$$(\mathbf{A} - \mathbf{I}\lambda_3)\mathbf{x}_{(3)} = \begin{bmatrix} 2-6 & 2 & -6 \\ 2 & -1-6 & -3 \\ -2 & -1 & 1-6 \end{bmatrix} \begin{bmatrix} x_{(3)1} \\ x_{(3)2} \\ x_{(3)3} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -4 & 2 & -6 \\ 2 & -7 & -3 \\ -2 & -1 & -5 \end{bmatrix} \begin{bmatrix} x_{(3)1} \\ x_{(3)2} \\ x_{(3)3} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

- Apply Gauss elimination to these equations
- Pick $x_{(3)3} = 1 \Rightarrow x_{(3)2} = -1$

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Example Results

$$\begin{bmatrix} -4 & 2 & -6 \\ 0 & -6 & -6 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_{(3)1} \\ x_{(3)2} \\ x_{(3)3} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$x_{(3)1} = \frac{6x_{(3)1} - 2x_{(3)1}}{-4} = \frac{6(1) - 2(-1)}{-4} = -2$$

- Eigenvalues $\lambda_1 = -2, \lambda_2 = -2, \lambda_3 = 6$ have eigenvectors shown below

$$\mathbf{x}_{(1)} = \begin{bmatrix} 3 \\ 0 \\ 2 \end{bmatrix} \quad \mathbf{x}_{(2)} = \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix} \quad \mathbf{x}_{(3)} = \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix}$$

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Eigenvector Linear Dependence

- Can we have $\alpha_1\mathbf{x}_{(1)} + \alpha_2\mathbf{x}_{(2)} + \alpha_3\mathbf{x}_{(3)} = \mathbf{0}$ without $\alpha_1 = \alpha_2 = \alpha_3 = 0$?

$$\alpha_1\mathbf{x}_{(1)} + \alpha_2\mathbf{x}_{(2)} + \alpha_3\mathbf{x}_{(3)} = \alpha_1 \begin{bmatrix} 3 \\ 0 \\ 2 \end{bmatrix} + \alpha_2 \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix} + \alpha_3 \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

- Homogenous equations have $\alpha_1 = \alpha_2 = \alpha_3 = 0$ if matrix has full rank

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Linear Dependence II

- Matrix has full rank if its determinant is not zero

$$\text{Det} \begin{bmatrix} 3 & -1 & -2 \\ 0 & 2 & -1 \\ 2 & 0 & 1 \end{bmatrix} = (3)(2)(1) + (0)(0)(-2) + (2)(-1)(-1) - (2)(2)(-2) - (0)(-1)(1) - (3)(0)(-1) = 15$$

- Since determinant is not zero, the only solution is $\alpha_1 = \alpha_2 = \alpha_3 = 0$, so eigenvectors are linearly independent

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In This Example $\mathbf{AX} = \mathbf{X}\Lambda$

$$\mathbf{AX} = \begin{bmatrix} 2 & 2 & -6 \\ 2 & -1 & -3 \\ -2 & -1 & 1 \end{bmatrix} \begin{bmatrix} 3 & -1 & -2 \\ 0 & 2 & -1 \\ 2 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -6 & 2 & -12 \\ 0 & -4 & -6 \\ -4 & 0 & 6 \end{bmatrix}$$

$$\mathbf{X}\Lambda = \begin{bmatrix} 3 & -1 & -2 \\ 0 & 2 & -1 \\ 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} -2 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 6 \end{bmatrix} = \begin{bmatrix} -6 & 2 & -12 \\ 0 & -4 & -6 \\ -4 & 0 & 6 \end{bmatrix}$$

Λ is diagonal matrix of eigenvalues
Will show this as general result next class

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Quadratic Forms

- Use general notation for transpose of column vector $x_{1m}^T = x_{m1}$

$$x^T = [x_{11}^T \quad x_{12}^T \quad \dots \quad x_{1n}^T] \quad x = \begin{bmatrix} x_{11} \\ x_{21} \\ \vdots \\ x_{n1} \end{bmatrix}$$

- Write general quadratic formula as a vector formula with symmetric a_{ik}

$$Q = \sum_{i=1}^N \sum_{k=1}^N a_{ik} x_i x_k = \mathbf{x}^T \mathbf{A} \mathbf{x}$$

$$(\mathbf{A}x)_{i1} = \sum_{k=1}^N a_{ik} x_{k1} \quad \mathbf{x}^T \mathbf{A} x = \sum_{i=1}^N x_{1i}^T (\mathbf{A}x)_{i1}$$

$$\mathbf{x}^T \mathbf{A} x = \sum_{i=1}^N \sum_{k=1}^N x_{1i}^T a_{ik} x_{k1} = \sum_{i=1}^N \sum_{k=1}^N a_{ik} x_i x_k$$

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Quadratic Forms II

- Theorem 2 in Chapter 8 of Kreyszig says that symmetric matrices have orthogonal eigenvectors
 - For an orthogonal matrix, $\mathbf{X}^{-1} = \mathbf{X}^T$
 - Can get *orthonormal* eigenvectors
- Theorem 4 in Chapter 8 of Kreyszig shows that if an $(n \times n)$ matrix, \mathbf{A} , has a basis set of eigenvectors as columns in an $(n \times n)$ matrix, \mathbf{X} , $\mathbf{D} = \mathbf{X}^{-1} \mathbf{A} \mathbf{X}$ is a diagonal matrix of eigenvalues

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Quadratic Forms III

- If $\mathbf{D} = \mathbf{X}^{-1} \mathbf{A} \mathbf{X}$, then $\mathbf{X} \mathbf{D} = \mathbf{X} \mathbf{X}^{-1} \mathbf{A} \mathbf{X} = \mathbf{A} \mathbf{X}$ and $\mathbf{X} \mathbf{D} \mathbf{X}^{-1} = \mathbf{A} \mathbf{X} \mathbf{X}^{-1} = \mathbf{A}$
- Quadratic forms, $Q = \mathbf{x}^T \mathbf{A} \mathbf{x}$, will have a symmetric \mathbf{A} matrix, which will have an orthonormal eigenvalue set: $\mathbf{X}^{-1} = \mathbf{X}^T$
- For $Q = \mathbf{x}^T \mathbf{A} \mathbf{x}$, with $\mathbf{A} = \mathbf{X} \mathbf{D} \mathbf{X}^{-1} = \mathbf{X} \mathbf{D} \mathbf{X}^T$ if \mathbf{X} is orthonormal, $\mathbf{X}^{-1} = \mathbf{X}^T$ so $Q = \mathbf{x}^T \mathbf{A} \mathbf{x} = \mathbf{x}^T \mathbf{X} \mathbf{D} \mathbf{X}^T \mathbf{x}$
- Define $\mathbf{y} = \mathbf{X}^T \mathbf{x} = \mathbf{X}^{-1} \mathbf{x}$ so $\mathbf{x} = \mathbf{X} \mathbf{y}$

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Quadratic Forms IV

- From $Q = \mathbf{x}^T \mathbf{X} \mathbf{D} \mathbf{X}^T \mathbf{x}$ and $\mathbf{y} = \mathbf{X}^T \mathbf{x}$: $Q = \mathbf{x}^T \mathbf{X} \mathbf{D} \mathbf{y}$
- We can write $\mathbf{x}^T \mathbf{X} = (\mathbf{X}^T \mathbf{x})^T = \mathbf{y}^T$ so $Q = \mathbf{y}^T \mathbf{D} \mathbf{y}$

$$Q = [y_1 \quad y_2 \quad y_3] \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

$$Q = [y_1 \quad y_2 \quad y_3] \begin{bmatrix} \lambda_1 y_1 \\ \lambda_2 y_2 \\ \lambda_3 y_3 \end{bmatrix} = \lambda_1 y_1^2 + \lambda_2 y_2^2 + \lambda_3 y_3^2$$

y_k are principal coordinates

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Sample Problem

- Find principal coordinates for quadratic equation: $Q = \mathbf{x}^T \mathbf{A} \mathbf{x} = 128$, where

$$\mathbf{A} = \begin{bmatrix} 17 & -15 \\ -15 & 17 \end{bmatrix} \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
- Solution steps:
 - Find eigenvalues (λ_1, λ_2) and normalized eigenvector matrix $\mathbf{X} = [\mathbf{x}_{(1)}, \mathbf{x}_{(2)}]$ for \mathbf{A}
 - Find principal coordinates, $\mathbf{y} = \mathbf{X}^T \mathbf{x}$
 - Solution is $Q = \mathbf{y}^T \mathbf{D} \mathbf{y} = \lambda_1 y_1^2 + \lambda_2 y_2^2$

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Sample Problem II

- Find principal coordinates for quadratic equation: $Q = \mathbf{A} \mathbf{x} = 128$

$$\mathbf{A} = \begin{bmatrix} 17 & -15 \\ -15 & 17 \end{bmatrix} \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
- $\text{Det}(\mathbf{A} - \lambda \mathbf{I}) = (17 - \lambda)^2 - (15)^2 = 0 \quad \lambda = \begin{cases} 2 \\ 32 \end{cases}$
- Find eigenvector for $\lambda_1 = 2$

$$(\mathbf{A} - \lambda \mathbf{I}) \mathbf{x} = \begin{bmatrix} 17 - 2 & -15 \\ -15 & 17 - 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

California State University Northridge *Both equations give $x_1 = x_2$* 32

Sample Problem III

- Find eigenvector for $\lambda_2 = 32$

$$(\mathbf{A} - \lambda \mathbf{I}) \mathbf{x} = \begin{bmatrix} 17 - 32 & -15 \\ -15 & 17 - 32 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Both equations give $x_1 = -x_2$
- For both eigenvectors pick $x_2 = 1$ to get eigenvectors $\mathbf{x}_{(1)} = [1 \ 1]^T$; $\mathbf{x}_{(2)} = [-1 \ 1]^T$
- Divide by $\sqrt{1^2 + 1^2} = \sqrt{2}$ for normalized $\mathbf{x}_{(1)} = [1/\sqrt{2} \ 1/\sqrt{2}]^T$; $\mathbf{x}_{(2)} = [-1/\sqrt{2} \ 1/\sqrt{2}]^T$

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Sample Problem IV

- Get \mathbf{X} from normalized eigenvectors and find $\mathbf{y} = \mathbf{X}^T \mathbf{x}$

$$\mathbf{x} = [\mathbf{x}_{(1)} \ \mathbf{x}_{(2)}] = \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$

$$\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \mathbf{x}^T \mathbf{x} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} x_1 + x_2 \\ -x_1 + x_2 \end{bmatrix}$$
- $Q = 128$ in terms of eigenvalues and \mathbf{y} 's

$$Q = \mathbf{y}^T \mathbf{D} \mathbf{y} = \lambda_1 y_1^2 + \lambda_2 y_2^2 = 2y_1^2 + 32y_2^2 = 128$$

$$2y_1^2/128 + 32y_2^2/128 = 1$$

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Sample Problem V

- Result can be modified into equation for an ellipse

$$\frac{Q}{128} = \frac{2y_1^2}{128} + \frac{32y_2^2}{128} = 1$$

$$\frac{y_1^2}{64} + \frac{y_2^2}{4} = 1$$

$$\frac{y_1^2}{8^2} + \frac{y_2^2}{2^2} = 1$$

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